

Big Ideas

- 1 Differential geometry is concerned with those properties of surface which depend on their behavior in a neighborhood of a point
- 2 According to our definition, each point p of a regular surface belongs to a coordinate neighborhood
- 3 The points of such a neighborhood are characterized by their coordinates and we should be able to define the local properties of interest in terms of these coordinates

A **diffeomorphism** is a differentiable function with a differentiable inverse.

Change of parameters Let p be a point of a regular surface S and let $x : U \subset \mathbb{R}^2 \rightarrow S, y : V \subset \mathbb{R}^2 \rightarrow S$ be 2 parameterizations of S such that $p \in x(U) \cap y(V) = W$. Then the change of coordinates $h = x^{-1} \circ y : y^{-1}(W) \rightarrow x^{-1}(W)$ is a diffeomorphism.

To check that a function is differentiable check that the differential is invertible.

Ladies and gentlemen! The time has come to give the definition of **MANIFOLD**:
An abstract surface (differentiable manifold of dimension 2) is a set S together with a family of one-to-one maps $x_\alpha : U_\alpha \rightarrow S$ of open sets $U_\alpha \subset \mathbb{R}^2$ into S such that,

- 1 $\bigcup_\alpha x_\alpha(U_\alpha) = S$. That is, the union over the images of the maps in our family of maps is the set S . So S is covered collectively by our family of maps.
- 2 For each pair α, β with $x_\alpha(U_\alpha) \cap x_\beta(U_\beta) = W \neq \emptyset$, we have that $x_\alpha^{-1}, x_\beta^{-1}(W)$ are open sets in \mathbb{R}^2 , and $x_\beta^{-1} \circ x_\alpha$ are differentiable maps

The pair (U_α, x_α) is called a differentiable structure on the manifold.